

MTH5113 (Winter 2022): Problem Sheet 9

Solutions

(1) (*Warm-up*)

(a) Consider the (real-valued) function

$$F : \mathbb{R}^3 \rightarrow \mathbb{R}, \quad F(x, y, z) = xy^2z^3,$$

as well as the parametric surface

$$\mathbf{P} : (0, 1) \times (0, 1) \rightarrow \mathbb{R}^3, \quad \mathbf{P}(u, v) = (1, u, v).$$

Compute the surface integral of F over $\mathbf{P}$.

(b) Consider the (real-valued) function

$$G : \mathbb{R}^3 \rightarrow \mathbb{R}, \quad G(x, y, z) = x^2 + y^2,$$

as well as the parametric surface

$$\tau : (0, 2\pi) \times (0, 1) \rightarrow \mathbb{R}^3, \quad \tau(u, v) = (v \cos u, v \sin u, v).$$

Compute the surface integral of G over τ .

(a) We begin by computing some required quantities. Differentiating $\mathbf{P}$ yields

$$\partial_1 \mathbf{P}(u, v) = (0, 1, 0), \quad \partial_2 \mathbf{P}(u, v) = (0, 0, 1),$$

and their cross product satisfies

$$\partial_1 \mathbf{P}(u, v) \times \partial_2 \mathbf{P}(u, v) = (1, 0, 0), \quad |\partial_1 \mathbf{P}(u, v) \times \partial_2 \mathbf{P}(u, v)| = 1.$$

Furthermore, observe that

$$F(\mathbf{P}(u, v)) = F(1, u, v) = u^2v^3.$$

Thus, by the definition of the (parametric) surface integral, we obtain

$$\begin{aligned}
\iint_{\mathbf{P}} F \, dA &= \iint_{(0,1) \times (0,1)} F(\mathbf{P}(u, v)) |\partial_1 \mathbf{P}(u, v) \times \partial_2 \mathbf{P}(u, v)| \, du \, dv \\
&= \int_0^1 \int_0^1 (u^2 v^3 \cdot 1) \, du \, dv \\
&= \int_0^1 u^2 \, du \int_0^1 v^3 \, dv \\
&= \frac{1}{12}.
\end{aligned}$$

(b) First, we differentiate τ ,

$$\partial_1 \tau(u, v) = (-v \sin u, v \cos u, 0), \quad \partial_2 \tau(u, v) = (\cos u, \sin u, 1),$$

and we compute their cross product:

$$\partial_1 \tau(u, v) \times \partial_2 \tau(u, v) = (v \cos u, v \sin u, -v), \quad |\partial_1 \tau(u, v) \times \partial_2 \tau(u, v)| = \sqrt{2} \cdot v.$$

In addition, note that

$$G(\tau(u, v)) = G(v \cos u, v \sin u, v) = v^2 \cos^2 u + v^2 \sin^2 u = v^2.$$

Using the above, we can now evaluate the given surface integral:

$$\begin{aligned}
\iint_{\tau} G \, dA &= \iint_{(0, 2\pi) \times (0, 1)} (v^2 \cdot \sqrt{2}v) \, du \, dv \\
&= \sqrt{2} \int_0^{2\pi} du \int_0^1 v^3 \, dv \\
&= \sqrt{2} \cdot 2\pi \cdot \frac{1}{4} \\
&= \frac{\pi}{\sqrt{2}}.
\end{aligned}$$

(2) (*Intro to surface integrals*) One can also define an intermediate notion of surface integration of vector fields over *parametric surfaces*. More specifically:

Definition. Let $\sigma : \mathbf{U} \rightarrow \mathbb{R}^3$ be a parametric surface, and let $\mathbf{F}$ be a vector field that

is defined on the image of γ . We then define the *surface integral* of $\mathbf{F}$ over σ by

$$\iint_{\sigma} \mathbf{F} \cdot d\mathbf{A} = \iint_{\mathbf{u}} \{\mathbf{F}(\sigma(\mathbf{u}, \mathbf{v})) \cdot [\partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v})]_{\sigma(\mathbf{u}, \mathbf{v})}\} d\mathbf{u} d\mathbf{v}.$$

(a) Consider the vector field $\mathbf{F}$ on $\mathbb{R}^3$ given by

$$\mathbf{F}(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \left(\mathbf{y}, \mathbf{z}^{5800} e^{\mathbf{x}^{2000} + 46\mathbf{y}^{1523}}, \mathbf{x} \right)_{(\mathbf{x}, \mathbf{y}, \mathbf{z})},$$

and let $\mathbf{P}$ be the parametric plane

$$\mathbf{P} : (0, 1) \times (0, 1) \rightarrow \mathbb{R}^3, \quad \mathbf{P}(\mathbf{u}, \mathbf{v}) = (1, \mathbf{u}, \mathbf{v}).$$

Compute the surface integral of $\mathbf{F}$ over $\mathbf{P}$.

(b) Consider the vector field $\mathbf{G}$ on $\mathbb{R}^3$ given by

$$\mathbf{G}(\mathbf{x}, \mathbf{y}, \mathbf{z}) = (\mathbf{z}, \mathbf{z}, \mathbf{x}^2 + \mathbf{y}^2)_{(\mathbf{x}, \mathbf{y}, \mathbf{z})},$$

and let τ be the parametric torus

$$\tau : (0, 2\pi) \times (0, 1) \rightarrow \mathbb{R}^3, \quad \tau(\mathbf{u}, \mathbf{v}) = (\mathbf{v} \cos \mathbf{u}, \mathbf{v} \sin \mathbf{u}, \mathbf{v}).$$

Compute the surface integral of $\mathbf{G}$ over τ .

(c) Consider the vector field $\mathbf{H}$ on $\mathbb{R}^3$ given by

$$\mathbf{H}(\mathbf{x}, \mathbf{y}, \mathbf{z}) = (-\mathbf{x}, -\mathbf{y}, \mathbf{z})_{(\mathbf{x}, \mathbf{y}, \mathbf{z})},$$

and let $\mathbf{q}$ be the (regular) parametric surface

$$\mathbf{q} : (0, 1) \times (0, 1) \rightarrow \mathbb{R}^3, \quad \mathbf{q}(\mathbf{u}, \mathbf{v}) = (\mathbf{u}, \mathbf{v}, \mathbf{u}^2 + \mathbf{v}^2).$$

Compute the surface integral of $\mathbf{H}$ over $\mathbf{q}$.

(a) We begin by computing some preliminary quantities:

$$\begin{aligned} \partial_1 \mathbf{P}(\mathbf{u}, \mathbf{v}) \times \partial_2 \mathbf{P}(\mathbf{u}, \mathbf{v}) &= (0, 1, 0) \times (0, 0, 1) \\ &= (1, 0, 0), \end{aligned}$$

$$\begin{aligned}\mathbf{F}(\mathbf{P}(u, v)) &= \mathbf{F}(1, u, v) \\ &= \left(u, v^{5800} e^{1+46u^{1523}}, 1 \right)_{\mathbf{P}(u,v)},\end{aligned}$$

for any $(u, v) \in (0, 1) \times (u, 1)$. The above then implies

$$\begin{aligned}\mathbf{F}(\mathbf{P}(u, v)) \cdot [\partial_1 \mathbf{P}(u, v) \times \partial_2 \mathbf{P}(u, v)]_{\mathbf{P}(u,v)} &= \left(u, v^{5800} e^{1+46u^{1523}}, 1 \right) \cdot (1, 0, 0) \\ &= u.\end{aligned}$$

Thus, recalling our definition of parametric surface integral, we obtain

$$\begin{aligned}\iint_{\mathbf{P}} \mathbf{F} \cdot d\mathbf{A} &= \iint_{(0,1) \times (0,1)} \{ \mathbf{F}(\mathbf{P}(u, v)) \cdot [\partial_1 \mathbf{P}(u, v) \times \partial_2 \mathbf{P}(u, v)]_{\mathbf{P}(u,v)} \} du dv \\ &= \iint_{(0,1) \times (0,1)} u du dv \\ &= \int_0^1 dv \int_0^1 u du \\ &= \frac{1}{2}.\end{aligned}$$

(b) First, we compute, for any $(u, v) \in (0, 2\pi) \times (0, 1)$,

$$\begin{aligned}\partial_1 \tau(u, v) \times \partial_2 \tau(u, v) &= (-v \sin u, v \cos u, 0) \times (\cos u, \sin u, 1) \\ &= (v \cos u, v \sin u, -v) \\ \mathbf{G}(\tau(u, v)) &= (v, v, v^2 \cos^2 u + v^2 \sin^2 u)_{\tau(u,v)} \\ &= (v, v, v^2)_{\tau(u,v)}.\end{aligned}$$

Combining the above, we then obtain

$$\begin{aligned}\mathbf{G}(\tau(u, v)) \cdot [\partial_1 \tau(u, v) \times \partial_2 \tau(u, v)]_{\tau(u,v)} &= (v, v, v^2) \cdot (v \cos u, v \sin u, -v) \\ &= v^2 \cos u + v^2 \sin u - v^3.\end{aligned}$$

Thus, by our given definition of surface integrals,

$$\begin{aligned}\iint_{\tau} \mathbf{G} \cdot d\mathbf{A} &= \iint_{(0,2\pi) \times (0,1)} \{ \mathbf{G}(\tau(u, v)) \cdot [\partial_1 \tau(u, v) \times \partial_2 \tau(u, v)]_{\tau(u,v)} \} du dv \\ &= \int_0^1 \int_0^{2\pi} (v^2 \cos u + v^2 \sin u - v^3) du dv\end{aligned}$$

$$\begin{aligned}
&= \int_0^1 (v^2 \sin u - v^2 \cos u - v^3 u) \Big|_{u=0}^{u=2\pi} dv \\
&= -2\pi \int_0^1 v^3 dv \\
&= -\frac{\pi}{2}.
\end{aligned}$$

(c) First, note that for any $(u, v) \times (0, 1) \times (0, 1)$, we have

$$\begin{aligned}
\partial_1 \mathbf{q}(u, v) \times \partial_2 \mathbf{q}(u, v) &= (1, 0, 2u) \times (0, 1, 2v) \\
&= (-2u, -2v, 1), \\
\mathbf{H}(\mathbf{q}(u, v)) &= (-u, -v, u^2 + v^2)_{\mathbf{q}(u, v)}, \\
\mathbf{H}(\mathbf{q}(u, v)) \cdot [\partial_1 \mathbf{q}(u, v) \times \partial_2 \mathbf{q}(u, v)]_{\mathbf{q}(u, v)} &= (-u, -v, u^2 + v^2) \cdot (-2u, -2v, 1) \\
&= 3u^2 + 3v^2.
\end{aligned}$$

Finally, using the above, we can evaluate the desired surface integral:

$$\begin{aligned}
\iint_{\mathbf{q}} \mathbf{H} \cdot d\mathbf{A} &= \iint_{(0,1) \times (0,1)} \{ \mathbf{H}(\mathbf{q}(u, v)) \cdot [\partial_1 \mathbf{q}(u, v) \times \partial_2 \mathbf{q}(u, v)]_{\mathbf{q}(u, v)} \} du dv \\
&= \int_0^1 \int_0^1 (3u^2 + 3v^2) du dv \\
&= 2.
\end{aligned}$$

(3) (*A Survey of Integration*) Let $\mathbf{S}$ denote the set

$$\mathbf{S} = \{(u, v, u^2 - v^2) \in \mathbb{R}^3 \mid (u, v) \in (0, 1) \times (0, 1)\}.$$

(a) Show that $\mathbf{S}$ is a surface. In addition, give an injective parametrisation of $\mathbf{S}$ whose image is precisely all of $\mathbf{S}$.

(b) Compute the surface integral over $\mathbf{S}$ of the real-valued function

$$F : \mathbb{R}^3 \rightarrow \mathbb{R}, \quad F(x, y, z) = xy.$$

(The double integral you get from expanding the surface integral is not so pleasant; you will probably have to use the method of substitution twice to compute it.)

(c) Let us also assign to $\mathbf{S}$ the *upward-facing orientation*, i.e. the orientation in the *positive*

z-direction. Then, compute the surface integral over S of the vector field

$$\mathbf{G}(x, y, z) = (xy^2, yx^2, 1)_{(x,y,z)}, \quad (x, y, z) \in \mathbb{R}^3.$$

(a) S is a surface, since it is the graph of the (smooth) function

$$f : (0, 1) \times (0, 1) \rightarrow \mathbb{R}, \quad f(u, v) = u^2 - v^2.$$

Furthermore, an injective parametrisation of all of S is given by

$$\sigma : (0, 1) \times (0, 1) \rightarrow S, \quad \sigma(u, v) = (u, v, u^2 - v^2).$$

(b) We begin by computing the partial derivatives of σ :

$$\partial_1 \sigma(u, v) = (1, 0, 2u), \quad \partial_2 \sigma(u, v) = (0, 1, -2v).$$

Taking a cross product of the above yields

$$\begin{aligned} \partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v) &= (-2u, 2v, 1), \\ |\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| &= \sqrt{1 + 4u^2 + 4v^2}. \end{aligned}$$

Now, by part (a), we know that σ is an injective parametrisation of S whose image is all of S . Thus, we can use σ to compute our surface integral:

$$\iint_S \mathbf{F} \, dA = \iint_{\sigma} \mathbf{F} \, dA.$$

To calculate the above, we first note that

$$\mathbf{F}(\sigma(u, v)) = \mathbf{F}(u, v, u^2 - v^2) = uv.$$

Thus, our surface integral can now be expanded as

$$\iint_S \mathbf{F} \, dA = \iint_{(0,1) \times (0,1)} \left(uv \sqrt{1 + 4u^2 + 4v^2} \right) \, du \, dv.$$

This can now be evaluated using Fubini's theorem and the method of substitution:

$$\begin{aligned}
\iint_S F \, dA &= \int_0^1 v \left[\int_0^1 u \sqrt{1 + 4u^2 + 4v^2} \, du \right] dv \\
&= \int_0^1 v \left[\frac{1}{12} (1 + 4u^2 + 4v^2)^{\frac{3}{2}} \right]_{u=0}^{u=1} dv \\
&= \frac{1}{12} \int_0^1 v \left[(5 + 4v^2)^{\frac{3}{2}} - (1 + 4v^2)^{\frac{3}{2}} \right] dv \\
&= \frac{1}{12} \cdot \frac{1}{20} \cdot \left[(5 + 4v^2)^{\frac{5}{2}} - (1 + 4v^2)^{\frac{5}{2}} \right]_{v=0}^{v=1} \\
&= \frac{1}{240} \left(9^{\frac{5}{2}} - 5^{\frac{5}{2}} - 5^{\frac{5}{2}} + 1^{\frac{5}{2}} \right) \\
&= \frac{61}{60} - \frac{5\sqrt{5}}{24}. \quad (\text{Sorry } \odot)
\end{aligned}$$

(Even if you were not able to get the final number, the most important part is that you can correctly expand the surface integral into a double integral.)

(c) First, recall from part (b) that

$$\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v) = (-2u, 2v, 1),$$

hence it follows that σ generates the upward-facing orientation of S . Consequently, we can use the parametrisation σ to compute our surface integrals:

$$\iint_S \mathbf{G} \cdot d\mathbf{A} = + \iint_U \{ \mathbf{G}(\sigma(u, v)) \cdot [\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)]_{\sigma(u, v)} \} du dv.$$

To calculate the above, we observe that

$$\mathbf{G}(\sigma(u, v)) = (uv^2, vu^2, 1)_{\sigma(u, v)},$$

and hence

$$\mathbf{G}(\sigma(u, v)) \cdot [\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)]_{\sigma(u, v)} = (uv^2, vu^2, 1) \cdot (-2u, 2v, 1) = 1.$$

Therefore, we conclude that

$$\iint_S \mathbf{G} \cdot d\mathbf{A} = \iint_{(0,1) \times (0,1)} 1 \, du dv = 1.$$

(4) [Marked] Let S denote the following surface:

$$S = \{(x, y, z) \in \mathbb{R}^3 \mid x = y^2 - z^2, 0 < y < 1, 0 < z < 1\}.$$

(a) Compute the surface integral over S of the function

$$G : \mathbb{R}^3 \rightarrow \mathbb{R}, \quad G(x, y, z) = yz.$$

(b) Let us also assign to S the *orientation in direction of increasing x -value*. Then, compute the surface integral over S of the vector field $\mathbf{H}$ on $\mathbb{R}^3$ given by

$$\mathbf{H}(x, y, z) = (y, 0, z)_{(x, y, z)},$$

(a) The first step is to parametrise S appropriately. For this, we set $u = y$ and $v = z$:

$$\sigma : (0, 1) \times (0, 1) \rightarrow S, \quad \sigma(u, v) = (u^2 - v^2, u, v).$$

Observe σ is injective, and its image is exactly S . [1 mark for correct parametrisation]

Furthermore, for any $(u, v) \in (0, 1) \times (0, 1)$, we compute

$$\begin{aligned} \partial_1 \sigma(u, v) &= (2u, 1, 0), \\ \partial_2 \sigma(u, v) &= (-2v, 0, 1), \\ \partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v) &= (1, -2u, 2v), \\ |\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| &= \sqrt{1 + 4u^2 + 4v^2}. \end{aligned}$$

Similarly, we have that

$$G(\sigma(u, v)) = uv.$$

We can now use σ and the above to compute the surface integral over S :

$$\begin{aligned} \iint_S G \, dA &= \iint_{\sigma} G \, dA \\ &= \iint_{(0,1) \times (0,1)} G(\sigma(u, v)) |\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| \, du \, dv \\ &= \int_0^1 v \int_0^1 u \sqrt{1 + 4u^2 + 4v^2} \, du \, dv. \end{aligned}$$

[1 mark for almost correct answer up to this point] From here, we directly compute

$$\begin{aligned}
 \iint_S G \, dA &= \frac{1}{12} \int_0^1 v(1 + 4u^2 + 4v^2)^{\frac{3}{2}} \Big|_{u=0}^{u=1} dv \\
 &= \frac{1}{12} \int_0^1 [v(5 + 4v^2)^{\frac{3}{2}} - v(1 + 4v^2)^{\frac{3}{2}}] dv \\
 &= \frac{1}{240} [(5 + 4v^2)^{\frac{5}{2}} - (1 + 4v^2)^{\frac{5}{2}}]_{v=0}^{v=1} \\
 &= \frac{1}{240} [(9^{\frac{5}{2}} - 5^{\frac{5}{2}}) - (5^{\frac{5}{2}} - 1^{\frac{5}{2}})] \\
 &= \frac{1}{240} (244 - 2 \cdot 5^{\frac{5}{2}}).
 \end{aligned}$$

[1 mark for somewhat correct integral]

(b) We can again use the parametrisation σ from (a). Observe that

$$[\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)]_{\sigma(u, v)} = (1, -2u, 2v)_{\sigma(u, v)},$$

which is in the normal direction generated by σ , points in the direction of increasing x (since the x -component is $+1$). Thus, σ generates our given orientation of S , and

$$\iint_S \mathbf{H} \cdot d\mathbf{A} = + \iint_{(0,1) \times (0,1)} \{\mathbf{H}(\sigma(u, v)) \cdot [\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)]_{\sigma(u, v)}\} \, du \, dv.$$

[1 mark for correct observation of orientation]

The integral can now be computed directly. First, we have

$$\mathbf{H}(\sigma(u, v)) = (u, 0, v)_{\sigma(u, v)}.$$

Thus, combining all the above, we obtain that

$$\begin{aligned}
 \iint_S \mathbf{H} \cdot d\mathbf{A} &= + \iint_{(0,1) \times (0,1)} [(u, 0, v) \cdot (1, -2u, 2v)] \, du \, dv \\
 &= \int_0^1 \int_0^1 (u + 2v^2) \, du \, dv \\
 &= \int_0^1 \left(\frac{1}{2} + 2v^2 \right) dv \\
 &= \frac{1}{2} + \frac{2}{3}
 \end{aligned}$$

$$= \frac{7}{6}.$$

[1 mark for an almost correct answer]

(5) [Tutorial]

(a) Consider the surface (*you may assume this is indeed a surface*)

$$\mathcal{P} = \{(u, v, u^4 + v) \in \mathbb{R}^3 \mid (u, v) \in (0, 1) \times (-1, 1)\}.$$

Compute the surface integral over $\mathcal{P}$ of the following function:

$$F : \mathbb{R}^3 \rightarrow \mathbb{R}, \quad F(x, y, z) = 6x^5.$$

(b) Consider the sphere,

$$\mathbb{S}^2 = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1\},$$

and let $\mathbb{S}^2$ be given the “outward-facing” orientation. Compute the surface integral over $\mathbb{S}^2$ of the vector field $\mathbf{F}$ on $\mathbb{R}^3$ defined by the formula

$$\mathbf{F}(x, y, z) = (0, 0, z^3)_{(x, y, z)}.$$

(a) The first step is to appropriately parametrise $\mathcal{P}$. Observe that the map

$$\sigma : (0, 1) \times (-1, 1) \rightarrow \mathcal{P}, \quad \sigma(u, v) = (u, v, u^4 + v)$$

is a parametrisation of $\mathcal{P}$. Moreover, note that σ is injective, and its image is all of $\mathcal{P}$. As a result, we have, from the definition of surface integrals,

$$\iint_{\mathcal{P}} F \, dA = \iint_{\sigma} F \, dA = \iint_{(0,1) \times (-1,1)} F(\sigma(u, v)) |\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| \, du \, dv.$$

Next, the partial derivatives of σ satisfy

$$\partial_1 \sigma(u, v) = (1, 0, 4u^3), \quad \partial_2 \sigma(u, v) = (0, 1, 1).$$

Thus, the required terms in the above integrand satisfy

$$\begin{aligned} |\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| &= |(-4u^3, -1, 1)| = \sqrt{2 + 16u^6}, \\ F(\sigma(u, v)) &= 6u^5. \end{aligned}$$

Combining all the above, we can now compute the surface integral as

$$\begin{aligned} \iint_{\mathcal{P}} F \, dA &= \int_{-1}^1 \int_0^1 6u^5 \sqrt{2 + 16u^6} \, du dv \\ &= 2 \int_0^1 6u^5 \sqrt{2 + 16u^6} \, du \\ &= 2 \cdot \frac{1}{16} \cdot \frac{2}{3} \cdot \left[(2 + 16u^6)^{\frac{3}{2}} \right]_{u=0}^{u=1} \\ &= \frac{13\sqrt{2}}{3}. \end{aligned}$$

(b) Recall (from lectures and the lecture notes) that the parametrisation of $\mathbb{S}^2$ given by

$$\rho : (0, 2\pi) \times (0, \pi) \rightarrow \mathbb{S}^2, \quad \rho(u, v) = (\cos u \sin v, \sin u \sin v, \cos v),$$

is injective, and that its image is “almost all” of $\mathbb{S}^2$ (the image excludes only two points and a semicircle). Moreover, from the usual computations, we have that

$$\partial_1 \rho(u, v) \times \partial_2 \rho(u, v) = -\sin v \cdot (\cos u \sin v, \sin u \sin v, \cos v) = -\sin v \cdot \rho(u, v).$$

In particular, the arrows

$$[\partial_1 \rho(u, v) \times \partial_2 \rho(u, v)]_{\rho(u, v)} = -\sin v \cdot \rho(u, v)_{\rho(u, v)},$$

which are normal to $\mathbb{S}^2$, point inward from $\mathbb{S}^2$. Thus, ρ generates the orientation opposite to our given orientation of $\mathbb{S}^2$, and hence we have that

$$\iint_{\mathbb{S}^2} \mathbf{F} \cdot d\mathbf{A} = - \iint_{(0, 2\pi) \times (0, \pi)} \{ \mathbf{F}(\rho(u, v)) \cdot [\partial_1 \rho(u, v) \times \partial_2 \rho(u, v)]_{\rho(u, v)} \} \, du dv.$$

Note the integrand satisfies

$$\mathbf{F}(\rho(u, v)) \cdot [\partial_1 \rho(u, v) \times \partial_2 \rho(u, v)]_{\rho(u, v)} = -\sin v (0, 0, \cos^3 v) \cdot (\cos u \sin v, \sin u \sin v, \cos v)$$

$$= -\sin v \cos^4 v.$$

As a result,

$$\begin{aligned} \iint_{\mathbb{S}^2} \mathbf{F} \cdot d\mathbf{A} &= \int_0^{2\pi} \int_0^\pi \sin v \cos^4 v \, dv du \\ &= 2\pi \cdot \frac{1}{5} [-\cos^5 v]_{v=0}^{v=\pi} \\ &= \frac{4\pi}{5}. \end{aligned}$$

(6) (*A-levels, revisited*)

(a) Show that the surface area of a *sphere of radius* $r > 0$,

$$S_r = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = r^2\},$$

is equal to $4\pi r^2$.

(b) Show that the area of the side of a cone with base radius $r > 0$ and height $h > 0$,

$$C_{r,h} = \left\{ (x, y, z) \in \mathbb{R}^3 \mid 0 < z < h, x^2 + y^2 = r^2 \left(1 - \frac{z}{h}\right)^2 \right\},$$

is equal to $\pi r \sqrt{r^2 + h^2}$.

(a) Similar to the case of a unit sphere, we see that

$$\rho_r : (0, 2\pi) \times (0, \pi) \rightarrow S_r, \quad \rho_r(u, v) = (r \cos u \sin v, r \sin u \sin v, r \cos v)$$

is an injective parametrisation of S_r , whose image is all of S_r except for two points and a semicircle. Moreover, a direct calculation (analogous to the one for $\mathbb{S}^2$) shows that

$$|\partial_1 \rho_r(u, v) \times \partial_2 \rho_r(u, v)| = |-r \sin v \cdot \rho_r(u, v)| = r^2 \sin v.$$

As a result, we obtain

$$\mathcal{A}(S_r) = \iint_{(0,2\pi) \times (0,\pi)} r^2 \sin v \, du dv = r^2 \int_0^{2\pi} du \int_0^\pi \sin v \, dv = 4\pi r^2.$$

(b) The main step is to parametrise $C_{r,h}$ correctly. For this, we can take

$$\sigma : (0, 2\pi) \times (0, h) \rightarrow C_{r,h}, \quad \sigma(u, v) = (r(1 - vh^{-1}) \cos u, r(1 - vh^{-1}) \sin u, v).$$

In particular, σ is injective, and its image is all of $C_{r,h}$ except for a line. (Plot this out and see for yourself!) Moreover, direct computations yield

$$\begin{aligned} \partial_1 \sigma(u, v) &= (-r(1 - vh^{-1}) \sin u, r(1 - vh^{-1}) \cos u, 0), \\ \partial_2 \sigma(u, v) &= (-rh^{-1} \cos u, -rh^{-1} \sin u, 1), \\ \partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v) &= (r(1 - vh^{-1}) \cos u, r(1 - vh^{-1}) \sin u, r^2 h^{-1}(1 - vh^{-1})), \\ |\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| &= r \left(1 - \frac{v}{h}\right) \sqrt{1 + \left(\frac{r}{h}\right)^2}. \end{aligned}$$

Combining the above, we conclude that the surface area is

$$\begin{aligned} \mathcal{A}(C_{r,h}) &= r \sqrt{1 + \left(\frac{r}{h}\right)^2} \iint_{(0,2\pi) \times (0,h)} \left(1 - \frac{v}{h}\right) du dv \\ &= 2\pi r \sqrt{1 + \left(\frac{r}{h}\right)^2} \int_0^h \left(1 - \frac{v}{h}\right) dv \\ &= 2\pi r \sqrt{1 + \left(\frac{r}{h}\right)^2} \cdot \frac{h}{2} \\ &= \pi r \sqrt{r^2 + h^2}. \end{aligned}$$

(7) (*Reversal of orientations*) Let $S \subseteq \mathbb{R}^3$ be an oriented surface, and let $\sigma : \mathcal{U} \rightarrow S$ be a parametrisation of S . Moreover, define the set

$$\mathcal{U}_r = \{(v, u) \mid (u, v) \in \mathcal{U}\}$$

and define the parametric surface

$$\sigma_r : \mathcal{U}_r \rightarrow \mathbb{R}^3, \quad \sigma_r(v, u) = \sigma(u, v).$$

In other words, σ_r is precisely σ but with the roles of u and v reversed.

(a) Show that for any $(u, v) \in \mathcal{U}$,

$$\partial_1 \sigma_r(v, u) \times \partial_2 \sigma_r(v, u) = -[\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)].$$

- (b) Show that σ_r is also a parametrisation of S , and that σ_r has the same image as σ .
- (c) Use the formula from part (a) to conclude that if σ generates an orientation $\mathbf{O}$ of S , then σ_r generates the orientation opposite to $\mathbf{O}$.

(a) We begin by relating the partial derivatives of σ and σ_r —for any $(v, u) \in \mathcal{U}_r$,

$$\begin{aligned}\partial_1 \sigma_r(v, u) &= \partial_v[\sigma_r(v, u)] = \partial_v[\sigma(u, v)] = \partial_2 \sigma(u, v), \\ \partial_2 \sigma_r(v, u) &= \partial_u[\sigma_r(v, u)] = \partial_u[\sigma(u, v)] = \partial_1 \sigma(u, v).\end{aligned}$$

As a result, using that the cross product is antisymmetric, we conclude that

$$\begin{aligned}\partial_1 \sigma_r(v, u) \times \partial_2 \sigma_r(v, u) &= \partial_2 \sigma(u, v) \times \partial_1 \sigma(u, v) \\ &= -[\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)].\end{aligned}$$

(b) First, suppose $\mathbf{p}$ is in the image of σ , so that $\mathbf{p} = \sigma(u, v)$ for some $(u, v) \in \mathcal{U}$. Then, by definition, $(v, u) \in \mathcal{U}_r$ and $\sigma_r(v, u) = \sigma(u, v) = \mathbf{p}$, and it follows that $\mathbf{p}$ is also in the image of σ_r . Conversely, if $\mathbf{p}$ is in the image of σ_r , then $\mathbf{p} = \sigma_r(v, u)$ for some $(v, u) \in \mathcal{U}_r$. This then implies $(u, v) \in \mathcal{U}$ and $\sigma(u, v) = \sigma_r(v, u) = \mathbf{p}$, and hence $\mathbf{p}$ is also in the image of σ . From the above, we conclude that σ and σ_r have the same image.

In particular, the above implies that the image of σ_r lies within S . Moreover, using the formula obtained from part (a), we have, for any $(v, u) \in \mathcal{U}_r$,

$$|\partial_1 \sigma_r(v, u) \times \partial_2 \sigma_r(v, u)| = |\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| \neq 0,$$

since σ is regular by assumption. This implies that σ_r is also regular.

Combining the above, we conclude that σ_r is indeed a parametrisation of S .

(c) For any point $\mathbf{p} = \sigma(u, v) = \sigma_r(v, u)$ of S (where $(u, v) \in \mathcal{U}$), we have that:

- The orientation generated by σ at $\mathbf{p}$ is given by

$$\mathbf{n}_\sigma(u, v) = + \left[\frac{\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)}{|\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)|} \right]_{\sigma(u, v)}.$$

- Recalling the result from (a), the orientation selected by σ_r at $\mathbf{p}$ is given by

$$\begin{aligned}\mathbf{n}_{\sigma_r}(\mathbf{v}, \mathbf{u}) &= + \left[\frac{\partial_1 \sigma_r(\mathbf{v}, \mathbf{u}) \times \partial_2 \sigma_r(\mathbf{v}, \mathbf{u})}{|\partial_1 \sigma_r(\mathbf{v}, \mathbf{u}) \times \partial_2 \sigma_r(\mathbf{v}, \mathbf{u})|} \right]_{\sigma_r(\mathbf{v}, \mathbf{u})} \\ &= - \left[\frac{\partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v})}{|\partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v})|} \right]_{\sigma(\mathbf{u}, \mathbf{v})} \\ &= -\mathbf{n}_\sigma(\mathbf{u}, \mathbf{v}).\end{aligned}$$

In particular, the above shows that σ_r generates the opposite unit normals as σ , and hence σ_r generates the orientation opposite to that of σ .

(8) (*The paradox of Gabriel's horn*) Consider the surface of revolution

$$\mathbf{G} = \left\{ (\mathbf{x}, \mathbf{y}, \mathbf{z}) \in \mathbb{R}^3 \mid \mathbf{y}^2 + \mathbf{z}^2 = \frac{1}{\mathbf{x}^2}, \mathbf{x} > 1 \right\},$$

which is sometimes nicknamed *Gabriel's horn*. (Before proceeding, you should search for “Gabriel's horn” on Google Images to see an illustration of $\mathbf{G}$.)

(a) Show that $\mathbf{G}$ has infinite surface area.

(b) Show that the interior of $\mathbf{G}$,

$$\mathbf{I} = \left\{ (\mathbf{x}, \mathbf{y}, \mathbf{z}) \in \mathbb{R}^3 \mid \mathbf{y}^2 + \mathbf{z}^2 \leq \frac{1}{\mathbf{x}^2}, \mathbf{x} > 1 \right\},$$

has finite volume.

In other words, *you can fill up the inside of the “horn” with a finite amount of paint, but you cannot paint the “horn” itself using a finite amount of paint!*

(a) To compute the surface area, we first parametrise $\mathbf{G}$ appropriately:

$$\sigma : (1, \infty) \times (0, 2\pi) \rightarrow \mathbf{G}, \quad \sigma(\mathbf{u}, \mathbf{v}) = (\mathbf{u}, \mathbf{u}^{-1} \cos \mathbf{v}, \mathbf{u}^{-1} \sin \mathbf{v}).$$

Note in particular that σ is injective, and its image is all of $\mathbf{G}$ except for a curve. (The reasoning here is analogous to that for Question (4).)

Next, we do some computations involving σ :

$$\partial_1 \sigma(\mathbf{u}, \mathbf{v}) = (1, -\mathbf{u}^{-2} \cos \mathbf{v}, -\mathbf{u}^{-2} \sin \mathbf{v}),$$

$$\begin{aligned}
\partial_2 \sigma(u, v) &= (0, -u^{-1} \sin v, u^{-1} \cos v), \\
\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v) &= (-u^{-3}, -u^{-1} \cos v, -u^{-1} \sin v), \\
|\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| &= u^{-1} \sqrt{1 + u^{-4}},
\end{aligned}$$

Combining the above with the definition of surface area, we conclude that

$$\begin{aligned}
A(G) &= \iint_{(1, \infty) \times (0, 2\pi)} |\partial_1 \sigma(u, v) \times \partial_2 \sigma(u, v)| \, du \, dv \\
&= \int_0^{2\pi} dv \int_1^\infty \frac{1}{u} \sqrt{1 + \frac{1}{u^4}} \, du.
\end{aligned}$$

Since $1 + u^{-4} \geq 1$ for all $u \in \mathbb{R}$, it follows that

$$A(G) \geq 2\pi \int_1^\infty \frac{1}{u} \, du = \lim_{u \nearrow \infty} \ln u - \ln 1 = +\infty.$$

Thus, we conclude that $A(G)$ is indeed infinite.

(b) Recall the volume of I is

$$V(I) = \iiint_I 1 \, dx \, dy \, dz.$$

The easiest way to describe I in a way that is convenient for integration is to do a change of variables and write y and z in terms of polar coordinates:

$$x = x, \quad y = r \cos \theta, \quad z = r \sin \theta.$$

In particular, I can be described in these new coordinates as

$$I = \{(x, r, \theta) \in \mathbb{R}^3 \mid x > 1, 0 \leq r \leq x^{-1}, 0 \leq \theta \leq 2\pi\}.$$

Note that the Jacobian with respect to this change of variables is

$$J = \det \frac{\partial(x, y, z)}{\partial(x, r, \theta)} = \det \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -r \sin \theta \\ 0 & \sin \theta & r \cos \theta \end{bmatrix} = r.$$

Thus, by the change of variables formula and Fubini's theorem, we have that

$$\begin{aligned}
 V(I) &= \int_0^{2\pi} \int_1^\infty \int_0^{x^{-1}} J \, dr dx d\theta \\
 &= \int_0^{2\pi} d\theta \int_1^\infty \int_0^{x^{-1}} r \, dr dx \\
 &= 2\pi \cdot \frac{1}{2} \int_1^\infty \frac{1}{x^2} \, dx \\
 &= \pi.
 \end{aligned}$$

Thus, the volume of I is indeed finite.