

# MTH5113 (Winter 2022): Problem Sheet 8

## Solutions

---

(1) (*Warm-up*) For each of the following parts:

- (i) Sketch the surface  $S$ .
- (ii) Draw the unit normal  $\mathbf{n}_p$  on the sketch from part (i).
- (iii) Give an informal description (e.g. “outward-facing”, “inward-facing”, “upward-facing”) of the side of  $S$  represented by the normal  $\mathbf{n}_p$ .

(a)  $S = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1\}$ , and

$$\mathbf{n}_p = (0, 1, 0)_{(0, -1, 0)}.$$

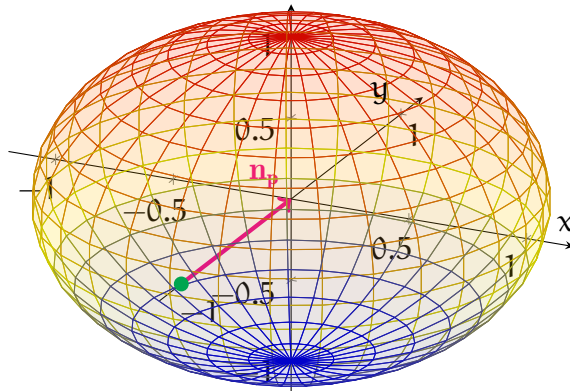
(b)  $S = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 = 1\}$ , and

$$\mathbf{n}_p = \left( \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, 0 \right)_{\left( \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, \frac{3}{4} \right)}.$$

(c)  $S = \{(x, y, z) \in \mathbb{R}^3 \mid z = x^2 + y^2\}$ , and

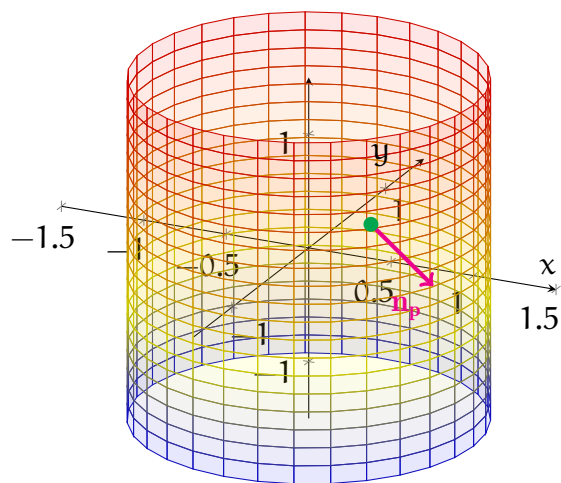
$$\mathbf{n}_p = \left( \frac{2}{3}, -\frac{2}{3}, -\frac{1}{3} \right)_{(1, -1, 2)}.$$

(a) The sketch of  $S$  and  $\mathbf{n}_p$  is given below:



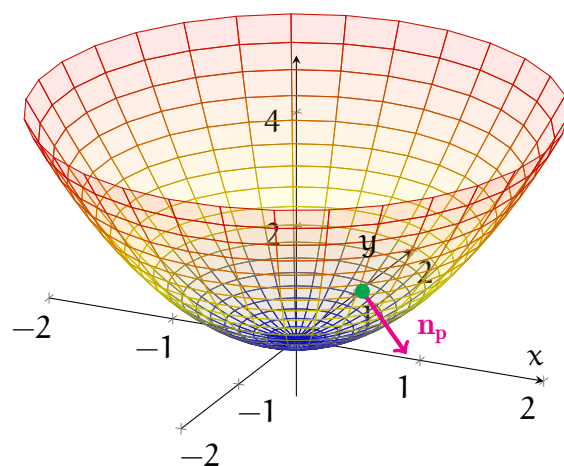
The unit normal  $\mathbf{n}_p$  represents the “inward-facing” orientation of  $S$ .

(b) The sketch of  $S$  and  $\mathbf{n}_p$  is given below:



The unit normal  $\mathbf{n}_p$  represents the “outward-facing” orientation of  $S$ .

(c) The sketch of  $S$  and  $\mathbf{n}_p$  is given below:



$\mathbf{n}_p$  represents the “outward”/“downward” (i.e. decreasing  $z$ -value) orientation of  $S$ .

(2) (*Warm-up*) Compute the surface areas of the following parametric surfaces:

(a) *Parametric torus:*

$$\alpha : (0, 2\pi) \times (0, 2\pi) \rightarrow \mathbb{R}^3, \quad \alpha(u, v) = ((2 + \cos u) \cos v, (2 + \cos u) \sin v, \sin u).$$

(See Question (8b) of Problem Sheet 1 for a plot of  $\alpha$ .)

(b) *Parallellogram spanned by vectors  $\mathbf{a}, \mathbf{b} \in \mathbb{R}^3$ :*

$$\beta : (0, 1) \times (0, 1) \rightarrow \mathbb{R}^3, \quad \beta(\mathbf{u}, \mathbf{v}) = \mathbf{u} \cdot \mathbf{a} + \mathbf{v} \cdot \mathbf{b}.$$

State your answer in terms of  $\mathbf{a}$  and  $\mathbf{b}$ .

(a) By direct computations (see also Question (1) of Problem Sheet 7), we obtain

$$\begin{aligned} \partial_1 \sigma(\mathbf{u}, \mathbf{v}) &= (-\sin \mathbf{u} \cos \mathbf{v}, -\sin \mathbf{u} \sin \mathbf{v}, \cos \mathbf{u}), \\ \partial_2 \sigma(\mathbf{u}, \mathbf{v}) &= (-(2 + \cos \mathbf{u}) \sin \mathbf{v}, (2 + \cos \mathbf{u}) \cos \mathbf{v}, 0), \\ \partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v}) &= -(2 + \cos \mathbf{u}) \cdot (\cos \mathbf{u} \cos \mathbf{v}, \cos \mathbf{u} \sin \mathbf{v}, \sin \mathbf{u}) \\ |\partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v})| &= |2 + \cos \mathbf{u}| \sqrt{\cos^2 \mathbf{u} \cos^2 \mathbf{v} + \cos^2 \mathbf{u} \sin^2 \mathbf{v} + \sin^2 \mathbf{v}} \\ &= 2 + \cos \mathbf{u}. \end{aligned}$$

Thus, by the definition of (parametric) surface area, we conclude that

$$\begin{aligned} \mathcal{A}(\alpha) &= \iint_{(0, 2\pi) \times (0, 2\pi)} |\partial_1 \alpha(\mathbf{u}, \mathbf{v}) \times \partial_2 \alpha(\mathbf{u}, \mathbf{v})| \, d\mathbf{u} d\mathbf{v} \\ &= \int_0^{2\pi} \int_0^{2\pi} (2 + \cos \mathbf{u}) \, d\mathbf{u} d\mathbf{v} \\ &= 2\pi \int_0^{2\pi} 2 \, d\mathbf{u} \\ &= 8\pi^2. \end{aligned}$$

(In the above, we applied Fubini's theorem and the fundamental theorem of calculus.)

(b) The first step is to take partial derivatives of  $\beta$ . In order to do this carefully, we expand  $\mathbf{a} = (\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3)$  and  $\mathbf{b} = (\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3)$  and then compute

$$\begin{aligned} \beta(\mathbf{u}, \mathbf{v}) &= (\mathbf{u}\mathbf{a}_1 + \mathbf{v}\mathbf{b}_1, \mathbf{u}\mathbf{a}_2 + \mathbf{v}\mathbf{b}_2, \mathbf{u}\mathbf{a}_3 + \mathbf{v}\mathbf{b}_3), \\ \partial_1 \beta(\mathbf{u}, \mathbf{v}) &= (\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3) = \mathbf{a}, \\ \partial_2 \beta(\mathbf{u}, \mathbf{v}) &= (\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3) = \mathbf{b}. \end{aligned}$$

In particular, we note that

$$|\partial_1 \beta(\mathbf{u}, \mathbf{v}) \times \partial_2 \beta(\mathbf{u}, \mathbf{v})| = |\mathbf{a} \times \mathbf{b}|,$$

which is a constant. As a result, we obtain, for the surface area,

$$\begin{aligned}\mathcal{A}(\beta) &= \iint_{(0,1) \times (0,1)} |\partial_1 \beta(u, v) \times \partial_2 \beta(u, v)| \, du dv \\ &= \int_0^1 \int_0^1 |\mathbf{a} \times \mathbf{b}| \, du dv \\ &= |\mathbf{a} \times \mathbf{b}|.\end{aligned}$$

(3) [Marked] Consider the *hyperboloid*

$$\mathcal{H} = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 - z^2 = 1\}.$$

(a) Find the tangent plane to  $\mathcal{H}$  at  $(1, -1, 1)$ .

(b) Find the unit normals to  $\mathcal{H}$  at  $(1, -1, 1)$ .

(c) Which of the two unit normals in (b) represents the “outward-facing” side of  $\mathcal{H}$ ?

(For part (c), you do not have to prove the answer. You can find the answer by sketching  $\mathcal{H}$  and the appropriate normals and then inspecting your sketch.)

(a) The first step is to give a parametrisation of  $\mathcal{H}$  that passes through  $(1, -1, 1)$ . One straightforward option is to take  $u = x$  and  $v = y$ , and with positive  $z$ -values:

$$\sigma : \{(u, v) \in \mathbb{R}^2 \mid u^2 + v^2 > 1\} \rightarrow \mathcal{H}, \quad \sigma(u, v) = \left(u, v, \sqrt{u^2 + v^2 - 1}\right).$$

The partial derivatives of  $\sigma$  are then given by:

$$\partial_1 \sigma(u, v) = \left(1, 0, \frac{u}{\sqrt{u^2 + v^2 - 1}}\right), \quad \partial_2 \sigma(u, v) = \left(0, 1, \frac{v}{\sqrt{u^2 + v^2 - 1}}\right).$$

[1 mark for an almost correct answer up to this point]

Note that  $(1, -1, 1) = \sigma(1, -1)$ . Thus, evaluating at  $(u, v) = (1, -1)$ , we obtain

$$\partial_1 \sigma(1, -1) = (1, 0, 1), \quad \partial_2 \sigma(1, -1) = (0, 1, -1).$$

As a result, the tangent plane to  $\mathcal{H}$  at  $(1, -1, 1)$  is given by

$$T_{(1, -1, 1)} \mathcal{H} = T_\sigma(1, -1) = \{\mathbf{a} \cdot (1, 0, 1)_{(1, -1, 1)} + \mathbf{b} \cdot (0, 1, -1)_{(1, -1, 1)} \mid \mathbf{a}, \mathbf{b} \in \mathbb{R}\}.$$

[1 mark for an almost correct answer]

(b) Taking a cross product of the partial derivatives in (a), we see that

$$\partial_1 \sigma(1, -1) \times \partial_2 \sigma(1, -1) = (-1, 1, 1), \quad |\partial_1 \sigma(1, -1) \times \partial_2 \sigma(1, -1)| = \sqrt{3}.$$

As a result, the unit normals to  $\mathcal{H}$  at  $(1, -1, 1) = \sigma(1, -1)$  are given by

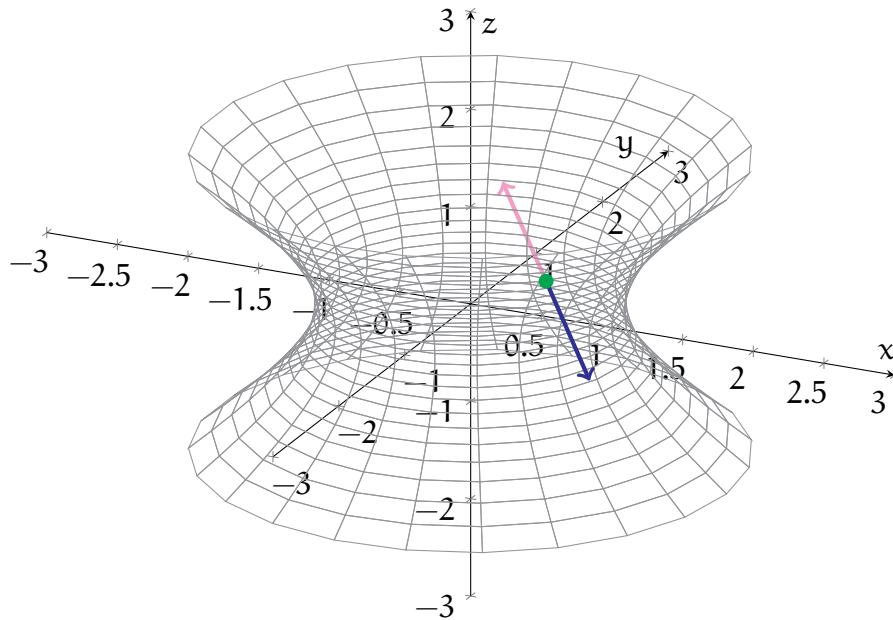
$$\begin{aligned} \mathbf{n}_\sigma^\pm(1, -1) &= \pm \left[ \frac{\partial_1 \sigma(1, -1) \times \partial_2 \sigma(1, -1)}{|\partial_1 \sigma(1, -1) \times \partial_2 \sigma(1, -1)|} \right]_{\sigma(1, -1)} \\ &= \pm \frac{1}{\sqrt{3}}(-1, 1, 1)_{(1, -1, 1)}. \end{aligned}$$

[2 marks for an almost correct answer]

(c) The outward-facing side of  $\mathcal{H}$  is captured by the unit normal

$$\mathbf{n}_\sigma^- = -\frac{1}{\sqrt{3}}(-1, 1, 1)_{(1, -1, 1)} = \frac{1}{\sqrt{3}}(1, -1, -1)_{(1, -1, 1)}.$$

One can see this by sketching  $\mathcal{H}$  and the two unit normals  $\mathbf{n}_\sigma^\pm$ :



(In the illustration,  $\mathcal{H}$  is drawn in grey,  $\mathbf{n}_\sigma^+$  is drawn in pink and is inward-facing, and  $\mathbf{n}_\sigma^-$  is drawn in blue and is outward-facing.) [1 mark for a reasonable attempt]

(4) [Tutorial] Consider the sphere

$$\mathbb{S}^2 = \{(\mathbf{x}, \mathbf{y}, \mathbf{z}) \in \mathbb{R}^3 \mid \mathbf{x}^2 + \mathbf{y}^2 + \mathbf{z}^2 = 1\}.$$

- (a) Find two parametrisations of  $\mathbb{S}^2$  such that the combined images of all these parametrisations cover all of  $\mathbb{S}^2$ .
- (b) Show that the unit normals to  $\mathbb{S}^2$  at any  $\mathbf{p} \in \mathbb{S}^2$  are given by  $\pm \mathbf{p}$ .
- (c) What choice of unit normals of  $\mathbb{S}^2$  defines the “outward-facing” orientation of  $\mathbb{S}^2$ ? What choice of unit normals of  $\mathbb{S}^2$  defines the “inward-facing” orientation of  $\mathbb{S}^2$ ?

(a) There are many different ways to do this, and we only give one answer here. For example, one could begin with the spherical coordinate parametrisation of  $\mathbb{S}^2$ :

$$\rho : \mathbb{R} \times (0, \pi) \rightarrow \mathbb{R}^3, \quad \rho(u, v) = (\cos u \sin v, \sin u \sin v, \cos v).$$

In particular,  $\rho$  is a regular parametrisation of  $\mathbb{S}^2$ , and its image is  $\mathbb{S}^2 \setminus \{(0, 0, \pm 1)\}$ —that is, all of  $\mathbb{S}^2$  except for the north and south poles. (See the lecture notes for this derivativation.)

To reach the points  $\{(0, 0, \pm 1)\}$  that are excluded by  $\rho$ , we can take another parametrisation that is obtained by switching around the  $x$ ,  $y$ , and  $z$ -components of  $\rho$ :

$$\tau : \mathbb{R} \times (0, \pi) \rightarrow \mathbb{R}^3, \quad \tau(u, v) = (\cos v, \cos u \sin v, \sin u \sin v).$$

From what we know about  $\rho$ , we see that the image of  $\tau$  is all of  $\mathbb{S}^2$  except for the points  $\{(\pm 1, 0, 0)\}$ . In particular, the images of  $\rho$  and  $\tau$  together cover all of  $\mathbb{S}^2$ .

Another strategy is to use stereographic projections—see Question (8) of Problem Sheet 7.

(b) The simplest way to do this is to note that  $\mathbb{S}^2$  is a level set,

$$\mathbb{S}^2 = \{(\mathbf{x}, \mathbf{y}, \mathbf{z}) \in \mathbb{R}^3 \mid s(\mathbf{x}, \mathbf{y}, \mathbf{z}) = 1\},$$

where  $s$  is the function

$$s : \mathbb{R}^3 \rightarrow \mathbb{R}, \quad s(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \mathbf{x}^2 + \mathbf{y}^2 + \mathbf{z}^2.$$

Taking a gradient of  $s$  yields, at each  $(x, y, z) \in \mathbb{S}^2$ ,

$$\nabla s(x, y, z) = (2x, 2y, 2z)_{(x,y,z)}, \quad |\nabla s(x, y, z)| = 2\sqrt{x^2 + y^2 + z^2} = 2,$$

where in the last step, we recalled that  $x^2 + y^2 + z^2 = 1$  for any  $(x, y, z) \in \mathbb{S}^2$ . Therefore, we conclude that the unit normals to  $\mathbb{S}^2$  at any  $\mathbf{p} = (x, y, z) \in \mathbb{S}^2$  are

$$\mathbf{n}_{\mathbf{p}}^{\pm} = \pm \frac{1}{|\nabla s(x, y, z)|} \cdot \nabla s(x, y, z) = \pm \frac{1}{2} \cdot (2x, 2y, 2z)_{(x,y,z)} = \pm \mathbf{p}_{\mathbf{p}}.$$

The unit normals can also be computed using the parametrisations from (a).

(c) The choice of the unit normal  $+\mathbf{p}_{\mathbf{p}}$  at each  $\mathbf{p} \in \mathbb{S}^2$  (notice that these vary smoothly with respect to  $\mathbf{p}$ ) defines the outward-facing orientation of  $\mathbb{S}^2$ . (In particular, if you plot the arrows  $+\mathbf{p}_{\mathbf{p}}$  on the sphere, you will see that they all point outwards from the sphere.)

On the other hand, the choice of the unit normal  $-\mathbf{p}_{\mathbf{p}}$  at each  $\mathbf{p} \in \mathbb{S}^2$  defines the inward-facing orientation of  $\mathbb{S}^2$ . (In particular, if you plot the arrows  $-\mathbf{p}_{\mathbf{p}}$  on the sphere, you will see that they all point inwards into the sphere.)

(5) (*Fun with graphs*) Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be a smooth function, and let

$$G_f = \{(x, y, z) \in \mathbb{R}^3 \mid z = f(x, y)\}$$

be the graph of  $f$ , which we know to be a surface. For any  $(x, y) \in \mathbb{R}^2$ :

(a) Find the tangent plane to  $G_f$  at  $(x, y, f(x, y))$ .

(b) Find the unit normals to  $G_f$  at  $(x, y, f(x, y))$ .

Give your answers in terms of  $f$  and its derivatives at  $(x, y)$ .

(a) First, the following is a parametrisation of  $G_f$ :

$$\sigma : \mathbb{R}^2 \rightarrow G_f, \quad \sigma(u, v) = (u, v, f(u, v)).$$

In particular, note that  $(x, y, f(x, y)) = \sigma(x, y)$ .

Taking partial derivatives of  $\sigma$  yields

$$\partial_1 \sigma(x, y) = (1, 0, \partial_1 f(x, y)), \quad \partial_2 \sigma(x, y) = (0, 1, \partial_2 f(x, y)).$$

Thus, by the definition of the tangent plane, we have

$$\begin{aligned} T_{(x,y,f(x,y))} G_f &= T_\sigma(x, y) \\ &= \left\{ a \cdot (1, 0, \partial_1 f(x, y))_{(x,y,f(x,y))} + b \cdot (0, 1, \partial_2 f(x, y))_{(x,y,f(x,y))} \mid a, b \in \mathbb{R} \right\}. \end{aligned}$$

(b) Continuing from part (a), we compute

$$\begin{aligned} \partial_1 \sigma(x, y) \times \partial_2 \sigma(x, y) &= (-\partial_1 f(x, y), -\partial_2 f(x, y), 1), \\ |\partial_1 \sigma(x, y) \times \partial_2 \sigma(x, y)| &= \sqrt{1 + [\partial_1 f(x, y)]^2 + [\partial_2 f(x, y)]^2}. \end{aligned}$$

As a result, the unit normals are given by

$$\begin{aligned} \mathbf{n}_{(x,y,f(x,y))}^\pm &= \pm \left[ \frac{\partial_1 \sigma(x, y) \times \partial_2 \sigma(x, y)}{|\partial_1 \sigma(x, y) \times \partial_2 \sigma(x, y)|} \right]_{\sigma(x,y)} \\ &= \pm \frac{1}{\sqrt{1 + [\partial_1 f(x, y)]^2 + [\partial_2 f(x, y)]^2}} \cdot (-\partial_1 f(x, y), -\partial_2 f(x, y), 1)_{(x,y,f(x,y))}. \end{aligned}$$

Alternatively, one can observe that  $G_f$  is the level set of the function

$$F(x, y, z) = z - f(x, y).$$

Moreover, the gradient of  $F$  satisfies

$$\nabla F(x, y, z) = (-\partial_1 f(x, y), -\partial_2 f(x, y), 1)_{(x,y,z)}.$$

Thus, the unit normals at  $(x, y, f(x, y))$  are also given by

$$\begin{aligned} \mathbf{n}_{(x,y,f(x,y))}^\pm &= \pm \frac{1}{|\nabla F(x, y, f(x, y))|} \cdot \nabla F(x, y, f(x, y)) \\ &= \pm \frac{1}{\sqrt{1 + [\partial_1 f(x, y)]^2 + [\partial_2 f(x, y)]^2}} \cdot (-\partial_1 f(x, y), -\partial_2 f(x, y), 1)_{(x,y,f(x,y))}. \end{aligned}$$

(6) (*Tangent planes revisited*) Let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  be a smooth function, and let

$$S = \{(x, y, z) \in \mathbb{R}^3 \mid f(x, y, z) = 0\}$$



be a level set of  $f$ . In addition, assume  $\nabla f(\mathbf{p})$  is nonzero for any  $\mathbf{p} \in S$ , so that  $S$  is a surface. Show that at each  $\mathbf{p} \in S$ , the tangent plane to  $S$  at  $\mathbf{p}$  satisfies

$$T_{\mathbf{p}}S = \{\mathbf{v}_{\mathbf{p}} \in T_{\mathbf{p}}\mathbb{R}^3 \mid \mathbf{v}_{\mathbf{p}} \cdot \nabla f(\mathbf{p}) = 0\}.$$

Let us denote the right-hand side of the above by  $V$ :

$$V = \{\mathbf{v}_{\mathbf{p}} \in T_{\mathbf{p}}\mathbb{R}^3 \mid \mathbf{v}_{\mathbf{p}} \cdot \nabla f(\mathbf{p}) = 0\}.$$

Since we have shown (see either the lectures or lecture notes) that  $\nabla f(\mathbf{p})$  is normal to every element of  $T_{\mathbf{p}}S$ , it follows that  $T_{\mathbf{p}}S \subseteq V$ .

Next, observe that  $V$  is a 2-dimensional vector space\*. Then, since  $V$  and  $T_{\mathbf{p}}S$  are both 2-dimensional subspaces of  $T_{\mathbf{p}}\mathbb{R}^3$ , and since  $V \subseteq T_{\mathbf{p}}S$ , it follows that  $V = T_{\mathbf{p}}S$ , as desired.

\* To actually prove that  $V$  is 2-dimensional, one can do a bit of linear algebra. For this, we let  $A : T_{\mathbf{p}}\mathbb{R}^3 \rightarrow \mathbb{R}$  denote the linear operator

$$A(\mathbf{v}_{\mathbf{p}}) = \mathbf{v}_{\mathbf{p}} \cdot \nabla f(\mathbf{p}).$$

Note that  $V$  is the kernel, or nullspace, of  $A$ . Since  $A$  is not everywhere zero, then  $\text{rank } A = 1$ . Since  $T_{\mathbf{p}}\mathbb{R}^3$  is 3-dimensional, we conclude that

$$\dim V = \dim(\ker A) = \dim T_{\mathbf{p}}\mathbb{R}^3 - \dim(\text{rank } A) = 3 - 1 = 2.$$

(7) (Surface area in higher dimensions)

- (a) Let  $\mathcal{P}$  be a parallelogram in  $\mathbb{R}^n$ , with two of its sides given by tangent vectors  $\mathbf{a}_{\mathbf{p}}$  and  $\mathbf{b}_{\mathbf{p}}$  (where  $\mathbf{a}, \mathbf{b}, \mathbf{p} \in \mathbb{R}^n$ ). Recall from lectures and the lecture notes that when  $n = 3$ , the area of  $\mathcal{P}$  is given by  $|\mathbf{a} \times \mathbf{b}|$ . Show that for general  $n$ , the area of  $\mathcal{P}$  satisfies

$$\mathcal{A}(\mathcal{P}) = \sqrt{\det \begin{bmatrix} \mathbf{a} \cdot \mathbf{a} & \mathbf{a} \cdot \mathbf{b} \\ \mathbf{b} \cdot \mathbf{a} & \mathbf{b} \cdot \mathbf{b} \end{bmatrix}}.$$

(In particular, when  $n \neq 3$ , we no longer have the cross product.)

- (b) Use the results from part (a) to give a reasonable definition of the surface area of a regular parametric surface  $\sigma : \mathcal{U} \rightarrow \mathbb{R}^n$ , for any dimension  $n$ .

(a) Letting  $\mathbf{a}_{\mathcal{P}}$  represent the “base” of  $\mathcal{P}$ , letting  $\mathbf{h}$  denote the “height” of  $\mathcal{P}$ , and letting  $\theta$  denote the angle between  $\mathbf{a}_{\mathcal{P}}$  and  $\mathbf{b}_{\mathcal{P}}$ , we see (as in the lectures) that

$$\mathcal{A}(\mathcal{P}) = |\mathbf{a}| \cdot \mathbf{h} = |\mathbf{a}||\mathbf{b}| \sin \theta.$$

Squaring the above and recalling the usual trigonometric identities, we see that

$$[\mathcal{A}(\mathcal{P})]^2 = |\mathbf{a}|^2 |\mathbf{b}|^2 \sin^2 \theta = |\mathbf{a}|^2 |\mathbf{b}|^2 - |\mathbf{a}|^2 |\mathbf{b}|^2 \cos^2 \theta.$$

Recalling the basic properties of dot products, the above can now be written as

$$[\mathcal{A}(\mathcal{P})]^2 = (\mathbf{a} \cdot \mathbf{a})(\mathbf{b} \cdot \mathbf{b}) - (\mathbf{a} \cdot \mathbf{b})^2 = \det \begin{bmatrix} \mathbf{a} \cdot \mathbf{a} & \mathbf{a} \cdot \mathbf{b} \\ \mathbf{b} \cdot \mathbf{a} & \mathbf{b} \cdot \mathbf{b} \end{bmatrix},$$

and the desired formula follows.

(b) Recall that when  $n = 3$ , the definition of surface area is given by

$$\mathcal{A}(\sigma) = \iint_{\mathbf{u}} |\partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v})| \, d\mathbf{u} d\mathbf{v},$$

and the integrand  $|\partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v})|$  represents the area of an “infinitesimal” parallelogram at  $\sigma(\mathbf{u}, \mathbf{v})$ . Thus, in higher dimensions, we can replace the above integrand by the corresponding formula for the area of a parallelogram in  $\mathbb{R}^n$  obtained in part (a):

$$\mathcal{A}(\sigma) = \iint_{\mathbf{u}} \mathcal{F}(\mathbf{u}, \mathbf{v}) \, d\mathbf{u} d\mathbf{v},$$

$$\mathcal{F}(\mathbf{u}, \mathbf{v}) = \sqrt{\det \begin{bmatrix} \partial_1 \sigma(\mathbf{u}, \mathbf{v}) \cdot \partial_1 \sigma(\mathbf{u}, \mathbf{v}) & \partial_1 \sigma(\mathbf{u}, \mathbf{v}) \cdot \partial_2 \sigma(\mathbf{u}, \mathbf{v}) \\ \partial_2 \sigma(\mathbf{u}, \mathbf{v}) \cdot \partial_1 \sigma(\mathbf{u}, \mathbf{v}) & \partial_2 \sigma(\mathbf{u}, \mathbf{v}) \cdot \partial_2 \sigma(\mathbf{u}, \mathbf{v}) \end{bmatrix}}.$$

(8) (*Confusion with Möbius bands*) Consider the parametric surface

$$\sigma : (-1, 1) \times \mathbb{R} \rightarrow \mathbb{R}^3, \quad \sigma(\mathbf{u}, \mathbf{v}) = \left( \left(1 - \frac{\mathbf{u}}{2} \sin \frac{\mathbf{v}}{2}\right) \cos \mathbf{v}, \left(1 - \frac{\mathbf{u}}{2} \sin \frac{\mathbf{v}}{2}\right) \sin \mathbf{v}, \frac{\mathbf{u}}{2} \cos \frac{\mathbf{v}}{2} \right),$$

and let  $\mathbf{M}$  be defined as the image of  $\sigma$ . One can, in fact, show that  $\mathbf{M}$  is a surface, and that  $\sigma$  is a parametrisation of  $\mathbf{M}$  whose image is all of  $\mathbf{M}$ . (*Here, you can assume both of these facts without proving them.*) In particular, this  $\mathbf{M}$  gives an explicit description of a *Möbius band*; see Figure 4.21 in the lecture notes for an illustration of  $\mathbf{M}$ .

Ms. Mistake (who is close friends with Mr. Error from Problem Sheet 4) decides to choose the following unit normals to  $\mathbf{M}$ :

$$\mathbf{n}_\sigma^+(\mathbf{u}, \mathbf{v}) = + \left[ \frac{\partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v})}{|\partial_1 \sigma(\mathbf{u}, \mathbf{v}) \times \partial_2 \sigma(\mathbf{u}, \mathbf{v})|} \right]_{\sigma(\mathbf{u}, \mathbf{v})}, \quad (\mathbf{u}, \mathbf{v}) \in (-1, 1) \times \mathbb{R}.$$

Ms. Mistake concludes that the  $\mathbf{n}_\sigma^+(\mathbf{u}, \mathbf{v})$ 's she chose define an orientation of  $\mathbf{M}$ , and hence  $\mathbf{M}$  is orientable! As a wise tutor for *MTH5113*, explain why Ms. Mistake is mistaken!

To explain this, one needs to understand how  $\sigma$  behaves. The first point to note that

$$\sigma(0, 0) = \sigma(0, 2\pi) = (1, 0, 0).$$

(The above is a special case of the following observation: every time the parameter  $\mathbf{v}$  increases by  $2\pi$ , the corresponding values  $\sigma(0, \mathbf{v})$  travel one full lap around  $\mathbf{M}$ .)

Next, let us compute the partial derivatives of  $\sigma$  (at  $\mathbf{u} = 0$  for simplicity):

$$\begin{aligned} \partial_1 \sigma(0, \mathbf{v}) &= \left( -\frac{1}{2} \sin \frac{\mathbf{v}}{2} \cos \mathbf{v}, -\frac{1}{2} \sin \frac{\mathbf{v}}{2} \sin \mathbf{v}, \frac{1}{2} \cos \frac{\mathbf{v}}{2} \right), \\ \partial_2 \sigma(0, \mathbf{v}) &= (-\sin \mathbf{v}, \cos \mathbf{v}, 0). \end{aligned}$$

Taking a cross product of the above yields

$$\begin{aligned} \partial_1 \sigma(0, \mathbf{v}) \times \partial_2 \sigma(0, \mathbf{v}) &= -\frac{1}{2} \left( \cos \mathbf{v} \cos \frac{\mathbf{v}}{2}, \sin \mathbf{v} \cos \frac{\mathbf{v}}{2}, \sin \frac{\mathbf{v}}{2} \right), \\ |\partial_1 \sigma(0, \mathbf{v}) \times \partial_2 \sigma(0, \mathbf{v})| &= \frac{1}{2}. \end{aligned}$$

As a result, at  $(\mathbf{u}, \mathbf{v}) = (0, \mathbf{v})$ , we have

$$\mathbf{n}_\sigma^+(0, \mathbf{v}) = - \left( \cos \mathbf{v} \cos \frac{\mathbf{v}}{2}, \sin \mathbf{v} \cos \frac{\mathbf{v}}{2}, \sin \frac{\mathbf{v}}{2} \right)_{\sigma(0, \mathbf{v})}.$$

In particular, at  $\mathbf{v} = 0$  and  $\mathbf{v} = 2\pi$ , we have

$$\mathbf{n}_\sigma^+(0, 0) = (-1, 0, 0)_{(1, 0, 0)}, \quad \mathbf{n}_\sigma^+(0, 2\pi) = (1, 0, 0)_{(1, 0, 0)},$$

that is, *the  $\mathbf{n}_\sigma^+(\mathbf{u}, \mathbf{v})$ 's include both unit normals of  $\mathbf{M}$  at  $(1, 0, 0)$ !* As a result, the  $\mathbf{n}_\sigma^+(\mathbf{u}, \mathbf{v})$ 's do *not* define an orientation of  $\mathbf{M}$  (since an orientation is by definition a choice of *only one* unit normal at each point), hence Ms. Mistake is indeed mistaken.

(More generally, the  $\mathbf{n}_\sigma^+(\mathbf{u}, \mathbf{v})$ 's include *both* unit normals to *any* point of  $\mathbf{M}$ .)